

1) One can show that for $\alpha(0) = p$, $\alpha'(0) = v$,

$$dF_p(v) = \left. \frac{d}{dt} F(\alpha(t)) \right|_{t=0} = \langle \text{grad} F(\alpha(t)), \alpha'(t) \big|_{t=0} \rangle \\ = \langle \text{grad} F(p), v \rangle$$

where \langle, \rangle denotes the inner product.

which is clearly independent of α , hence well-defined.

Since the inner product is well-defined, we have for $v, w \in T_p M$, $\alpha \in \mathbb{R}$,

$$dF_p(\alpha v + w) = \langle \text{grad} F(p), \alpha v + w \rangle \\ = \alpha \langle \text{grad} F(p), v \rangle + \langle \text{grad} F(p), w \rangle \\ = \alpha dF_p(v) + dF_p(w).$$

So dF_p is linear.

Alternatively, for linearity, here to show

$$dF_p(\lambda v) = \lambda dF_p(v) \text{ by taking } \beta(t) := \alpha(\lambda t) = X(u(\lambda t), v(\lambda t))$$

so that if $\alpha'(0) = v$, then $\beta'(0) = \lambda v$ and then proceed from definition, and similarly for $v+w$ so that if

$\alpha'(0) = v$, $\beta'(0) = w$, then choose γ so that

$\gamma'(0) = v+w$ and use γ to show

$$dF_p(v+w) = dF_p(v) + dF_p(w).$$

2) $\alpha: (0, \frac{\pi}{2}) \rightarrow xz$ plane by

$$\alpha(t) = (\sin t, 0, \cos t + \ln \tan \frac{t}{2})$$

Surface of revolution by rotating α about z -axis is given by

$$X(t, \theta) = (\sin t \cos \theta, \sin t \sin \theta, \cos t + \ln \tan \frac{t}{2})$$

$$\text{Then } X_t = (\cos t \cos \theta, \cos t \sin \theta, -\sin t + \frac{1}{\sin t})$$

$$X_\theta = (-\sin t \sin \theta, \sin t \cos \theta, 0)$$

$$E = \langle X_t, X_t \rangle = \frac{\cos^2 t}{\sin^2 t}$$

$$F = \langle X_t, X_\theta \rangle = 0$$

$$G = \langle X_\theta, X_\theta \rangle = \sin^2 t$$

$$EG - F^2 = \cos^2 t \Rightarrow |X_t \times X_\theta| = \cos t$$

$$X_t \times X_\theta = (-\cos^2 t \cos \theta, -\cos^2 t \sin \theta, \sin t \cos t)$$

$$\Rightarrow N = (-\cos t \cos \theta, -\cos t \sin \theta, \sin t)$$

$$X_{tt} = (-\sin t \cos \theta, \sin t \sin \theta, -\cos t - \frac{\cos t}{\sin^2 t})$$

$$X_{t\theta} = (-\cos t \sin \theta, \cos t \cos \theta, 0)$$

$$X_{\theta\theta} = (-\sin t \cos \theta, -\sin t \sin \theta, 0)$$

$$e = \langle N, X_{tt} \rangle = \frac{-\cos t}{\sin t}$$

$$f = \langle N, X_{t\theta} \rangle = 0$$

$$g = \langle N, X_{\theta\theta} \rangle = \sin t \cos t$$

$$\text{Then } k(p) = \frac{eg - f^2}{Eg - F^2} = \frac{-\cos^2 t}{\cos^2 t} = -1$$

3) $M = \{(x, y, z) : z = x^2 + ky^2\}$ $k > 0$. Can be parametrized by $X(u, v) = (u, v, u^2 + kv^2)$.

$$\text{Then } X_u = (1, 0, 2u)$$

$$X_v = (0, 1, 2kv)$$

When $p = (0, 0, 0)$, $u = v = 0$, and $X_u = e_1$
 $X_v = e_2$.

So at $p = (0, 0, 0)$, e_1, e_2 form a basis of $T_p M$.

$$N = \frac{1}{\sqrt{1 + 4u^2 + 4k^2v^2}} (-2u, -2kv, 1)$$

Note that this satisfies $\langle N, e_3 \rangle = \frac{1}{\sqrt{1 + 4u^2 + 4k^2v^2}} > 0$.

$$E = \langle X_u, X_u \rangle = 1 + 4u^2 \quad \text{at } p, \quad E|_p = 1$$

$$F = \langle X_u, X_v \rangle = 4kuv \quad F|_p = 0$$

$$G = \langle X_v, X_v \rangle = 1 + 4k^2v^2 \quad G|_p = 1$$

$$X_{uu} = (0, 0, 2), \quad X_{uv} = (0, 0, 0), \quad X_{vv} = (0, 0, 2k)$$

$$\text{So } e = \langle N, X_{uu} \rangle = \frac{2}{\sqrt{1 + 4u^2 + 4k^2v^2}} \quad \text{at } p, \quad e|_p = 2$$

$$f = \langle N, X_{uv} \rangle = 0 \quad \text{at } p, \quad f|_p = 0$$

$$g = \langle N, X_{vv} \rangle = \frac{2k}{\sqrt{1 + 4u^2 + 4k^2v^2}} \quad \text{at } p, \quad g|_p = 2k$$

$$\begin{aligned}
 \text{So at } p, \quad S_p &= \frac{1}{EG-F^2} \begin{pmatrix} e & f \\ f & g \end{pmatrix} \begin{pmatrix} G & -F \\ -F & E \end{pmatrix} \Big|_p \\
 &= \begin{pmatrix} 2 & 0 \\ 0 & 2k \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} 2 & 0 \\ 0 & 2k \end{pmatrix}.
 \end{aligned}$$

So the principal curvatures of M at $p=(0,0,0)$ are $k_1=2$, $k_2=2k$. ($k>0$).

$$\Rightarrow \frac{\langle d(fN)(v_1) \times d(fN)(v_2), N \rangle}{f^2} = \frac{f^2 \langle dN_p(v_1) \times dN_p(v_2), N \rangle}{f^2} \\ = K(p) \text{ as required.}$$

$$\text{ii) } h(x, y, z) = \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

$$f(x, y, z) = \left(\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4} \right)^{\frac{1}{2}} \Big|_{h.}$$

We can take

$$N = \frac{dh}{|dh|} = \frac{dh}{\left(\left(\frac{2x}{a^2} \right)^2 + \left(\frac{2y}{b^2} \right)^2 + \left(\frac{2z}{c^2} \right)^2 \right)^{\frac{1}{2}}} = \frac{dh}{\left(4 \left(\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4} \right) \right)^{\frac{1}{2}}} = \frac{dh}{2f}$$

For a vector $v = (v_1, v_2, v_3)$, we have

$$d(fN)(v) = \frac{1}{2} dh(v) = \frac{1}{2} \left(\frac{2x}{a^2} dx + \frac{2y}{b^2} dy + \frac{2z}{c^2} dz \right) (v_1, v_2, v_3) \\ = \left(\frac{v_1}{a^2}, \frac{v_2}{b^2}, \frac{v_3}{c^2} \right).$$

Let $\{u, v\}$ be an orthonormal basis, $N = u \times v = (n_1, n_2, n_3)$, then by (i), we have

$$K = \frac{1}{f^2} \begin{vmatrix} \frac{u_1}{a^2} & \frac{u_2}{b^2} & \frac{u_3}{c^2} \\ \frac{v_1}{a^2} & \frac{v_2}{b^2} & \frac{v_3}{c^2} \\ n_1 & n_2 & n_3 \end{vmatrix} = \frac{1}{f^2 a b c^2} \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ a^2 n_1 & b^2 n_2 & c^2 n_3 \end{vmatrix}$$

$$= \frac{1}{f^2 a^2 b^2 c^2} \langle u \times v, (a^2 n_1, b^2 n_2, c^2 n_3) \rangle$$

$$= \frac{1}{f^2 a^2 b^2 c^2} \langle N, (a^2 n_1, b^2 n_2, c^2 n_3) \rangle$$

$$= \frac{1}{f^2 a^2 b^2 c^2} \langle (a^2, b^2, c^2), (n_1^2, n_2^2, n_3^2) \rangle.$$

From $N = \frac{dh}{2f}$, we get

$$(n_1, n_2, n_3) = \left(\frac{x}{fa^2}, \frac{y}{fb^2}, \frac{z}{fc^2} \right)$$

$$\Rightarrow (n_1^2, n_2^2, n_3^2) = \left(\frac{x^2}{f^2 a^4}, \frac{y^2}{f^2 b^4}, \frac{z^2}{f^2 c^4} \right)$$

$$\text{So } \langle (a^2, b^2, c^2), (n_1^2, n_2^2, n_3^2) \rangle$$

$$= \langle (a^2, b^2, c^2), \left(\frac{x^2}{f^2 a^4}, \frac{y^2}{f^2 b^4}, \frac{z^2}{f^2 c^4} \right) \rangle$$

$$= \frac{x^2}{f^2 a^2} + \frac{y^2}{f^2 b^2} + \frac{z^2}{f^2 c^2}$$

$$\text{So } K = \frac{1}{f^2 a^2 b^2 c^2} \left(\frac{x^2}{f^2 a^2} + \frac{y^2}{f^2 b^2} + \frac{z^2}{f^2 c^2} \right) = \frac{1}{f^4 a^2 b^2 c^2} \underbrace{\left(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \right)}_{=h=1}$$

$$= \frac{1}{f^4 a^2 b^2 c^2} \text{ as required } \%$$

5) Given the parametrization of the catenoid

$$X(u, v) = (a \cosh(v) \cos(u), a \cosh(v) \sin(u), av) \quad a > 0.$$

$$X_u = (-a \cosh(v) \sin(u), a \cosh(v) \cos(u), 0)$$

$$X_v = (a \sinh(v) \cos(u), a \sinh(v) \sin(u), a)$$

$$X_u \times X_v = (a^2 \cosh(v) \cos(u), a^2 \cosh(v) \sin(u), -a^2 \cosh(v) \sinh(v))$$

$$|X_u \times X_v| = a^2 \cosh^2(v)$$

$$\text{So } N = \left(\frac{\cos(u)}{\cosh(v)}, \frac{\sin(u)}{\cosh(v)}, \frac{-\sinh(v)}{\cosh(v)} \right)$$

$$S_p(X_u) = -N_u = \left(\frac{\sin(u)}{\cosh(v)}, \frac{-\cos(u)}{\cosh(v)}, 0 \right)$$

$$S_p(X_v) = -N_v = (\cos(u) \tanh(v) \operatorname{sech}(v), \sin(u) \tanh(v) \operatorname{sech}(v), \operatorname{sech}^2(v))$$

$$\text{So } E = \langle X_u, X_u \rangle = a^2 \cosh^2(v)$$

$$F = \langle X_u, X_v \rangle = 0$$

$$G = \langle X_v, X_v \rangle = a^2 \cosh^2(v).$$

$$e = \langle S_p(X_u), X_u \rangle = -a$$

$$f = \langle S_p(X_u), X_v \rangle = 0$$

$$g = \langle S_p(X_v), X_v \rangle = a.$$

$$H(p) = \frac{\frac{1}{2} eG - 2fF + gE}{EG - F^2} = \frac{\frac{1}{2} (-a^3 \cosh^2(v) + a^3 \cosh^2(v))}{a^4 \cosh^4(v)} = 0.$$